

# The mathematical theory of contextuality

## Lecture 2: sheaf-theoretic formulation

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In terms of measures:

$$\mathbf{D}(f)(d)(S) = d(f^{-1}(S)).$$



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Normalization corresponds to this monad being **affine**

$$D(\mathbf{1}) \cong \mathbf{1}.$$



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Features in **tropical geometry** (the **max-plus** semiring).

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This yields a functor  $\mathcal{D}_R : \mathbf{Set} \rightarrow \mathbf{Set}$ .

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Spelling this out, for each open set  $U \subseteq X$ , we have a set  $P(U)$ , and whenever  $U \subseteq V$ , there is a function, the **restriction map**

$$\rho_U^V : P(V) \rightarrow P(U)$$

subject to the functoriality requirements: if  $U \subseteq V \subseteq W$ , then

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Functoriality is easily verified: in this notation

$$(f|_V)|_U = f|_U.$$

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- **Morphisms** of presheaves are just natural transformations.
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- However, there is an important conceptual aspect which should be understood. Presheaves allow us to formalise the concept of **variable set**. The variation is essentially over **contexts**. So presheaves provide the natural setting for talking about contextuality!

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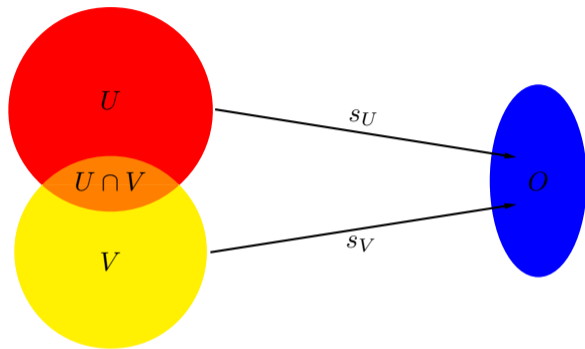
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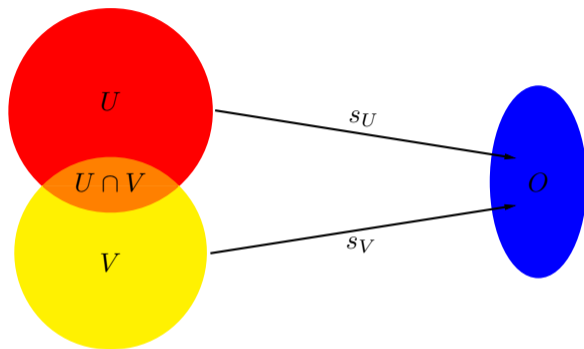
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The presheaf  $P$  is a **sheaf** if for every open cover  $\mathcal{U}$ , it satisfies the sheaf condition for  $\mathcal{U}$ .

## Gluing functional sections



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If  $s_U|_{U \cap V} = s_V|_{U \cap V}$ , they can be glued to form

$$s : U \cup V \longrightarrow O$$

such that  $s|_U = s_U$  and  $s|_V = s_V$ .

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In particular, this is one of the main intuitions behind **sheaf cohomology**.

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A useful generalization: we have a set  $O_x$  of outcomes for each measurement  $x$ . Then  $\mathcal{E}(U) = \prod_{x \in U} O_x$ . Restriction is by projection.

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As we shall see, contextuality arises exactly where the sheaf property **fails**. Contextuality witnesses – Bell tests and other forms we will study – are **exactly** witnesses to this failure – **obstructions** to gluing.

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This is in fact the content of the Conway-Kochen “Free Will Theorem”.

# Contextual Probability Theory

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Rather than a fixed probability space  $(X, d)$ ,  $d \in \mathcal{D}_R(X)$ , we can now consider a **variable probability space**

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We shall now see how this arises naturally in some important situations.

# A Probabilistic Model Of An Experiment

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Example: The Bell Model

| A     | B     | (0,0) | (1,0) | (0,1) | (1,1) |
|-------|-------|-------|-------|-------|-------|
| $a_1$ | $b_1$ | $1/2$ | 0     | 0     | $1/2$ |
| $a_1$ | $b_2$ | $3/8$ | $1/8$ | $1/8$ | $3/8$ |
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The entry in row 2 column 3 says:

*If Alice looks at  $a_1$  and Bob looks at  $b_2$ , then 1/8th of the time, Alice sees a 0 and Bob sees a 1.*

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Each row of the table specifies a **probability distribution** on events  $O^C$  for a given choice of measurements  $C$ .

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The fact that the behaviour of these observable outcomes cannot be accounted for by some context-independent global description of reality corresponds to the geometric fact that these local sections cannot be glued together into a **global section**.

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The quantum phenomena of **non-locality** and **contextuality** correspond exactly to the existence of obstructions to global sections in this sense.

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If  $d$  is a global section for the model  $\{e_C\}$ , we recover the predictions of the model by **averaging over the values of these hidden variables**:

$$e_C(s) = d|_C(s) = \sum_{s' \in \mathcal{E}(X), s'|_C = s} d(s') = \sum_{s' \in \mathcal{E}(X)} \delta_{s'|_C(s)} \cdot d(s').$$

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We have a sheaf of sets over  $\mathcal{P}(X)$ , namely  $\mathcal{E} :: U \longmapsto O^U$  with restriction

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Each  $s \in \mathcal{E}(U)$  is a **section**, and, in particular,  $g \in \mathcal{E}(X)$  is a **global section**.

## Sheaf formulation of contextuality

Measurement scenarios  $\langle X, \mathcal{M}, O \rangle$  :

- $X$  is a set of variables or measurement labels. Sufficient to consider finite discrete space — the base space of the bundle.
- $\mathcal{M} = \{C_i\}_{i \in I}$  set of **contexts** *i.e.* co-measurable variables. In quantum terms, compatible observables.
- $O$  is set of outcomes or values for the variables, which we take to be the same in each fibre.

We have a sheaf of sets over  $\mathcal{P}(X)$ , namely  $\mathcal{E} :: U \longmapsto O^U$  with restriction

$$\mathcal{E}(U \subseteq U') : \mathcal{E}(U') \longrightarrow \mathcal{E}(U) :: s \longmapsto s|_U .$$

Each  $s \in \mathcal{E}(U)$  is a **section**, and, in particular,  $g \in \mathcal{E}(X)$  is a **global section**.

A probability table can be represented by a family  $\{p_C\}_{C \in \mathcal{M}}$  with  $p_C$  a probability distribution on  $\mathcal{E}(C) = O^C$ , where contexts  $C$  corresponds to the rows of the table.

# Empirical Models

## Empirical Models

The logical and strong forms of contextuality are concerned with **possibilities**, which can be represented by a subpresheaf  $\mathcal{S}$  of  $\mathcal{E}$ , where for each context  $U \subseteq X$ ,  $\mathcal{S}(U) \subseteq O^U$  is the set of all possible outcomes.

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We can use this formalisation to characterize contextuality as follows.

## Definition

For any empirical model  $\mathcal{S}$ :

- For all  $C \in \mathcal{M}$  and  $s \in \mathcal{S}(C)$ ,  $\mathcal{S}$  is **logically contextual** at  $s$ , written  $\text{LC}(\mathcal{S}, s)$ , if  $s$  is not a member of any compatible family.
- $\mathcal{S}$  is **strongly contextual**, written  $\text{SC}(\mathcal{S})$ , if  $\text{LC}(\mathcal{S}, s)$  for all  $s$ . Equivalently, if it has no global section, *i.e.* if  $\mathcal{S}(X) = \emptyset$ .



## Two views of variation: indexed and fibred

Indexed family of sets  $\{X_i\}_{i \in I}$ .

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Sheaves on  $X$  are equivalently formulated as continuous maps  $p : Y \rightarrow X$  which are **local homeomorphisms** (*espaces étalé*).



# Bundle Pictures

## Logical Contextuality

- Ignore precise probabilities
- Events are possible or not
- E.g. the Hardy model:

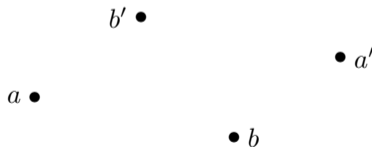
|        | 00 | 01 | 10 | 11 |
|--------|----|----|----|----|
| $ab$   | ✓  | ✓  | ✓  | ✓  |
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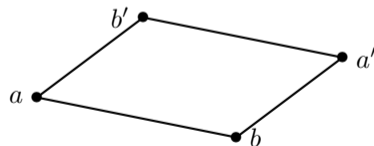


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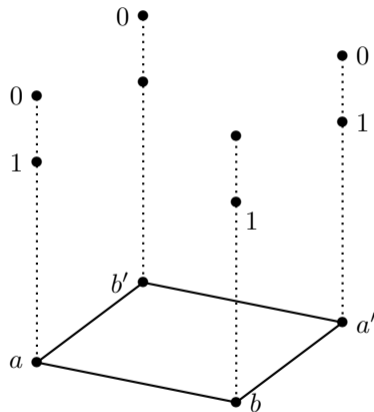


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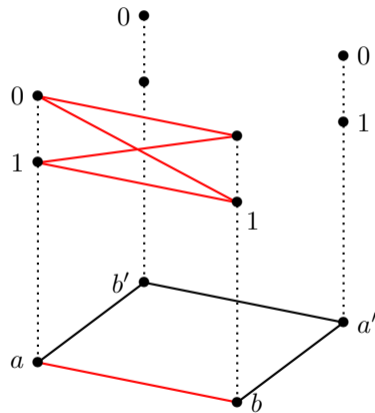


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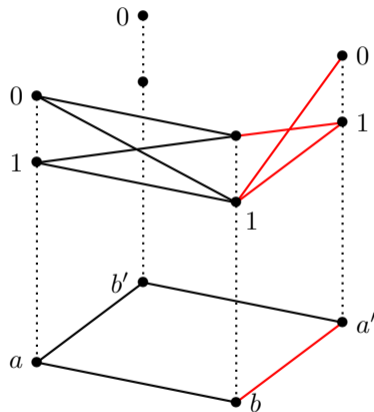


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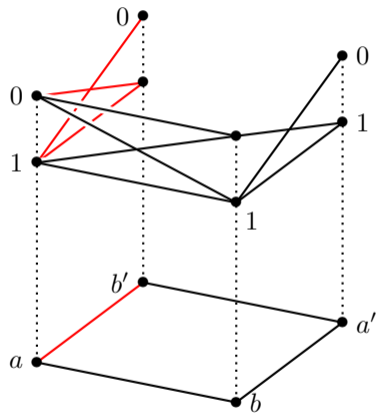


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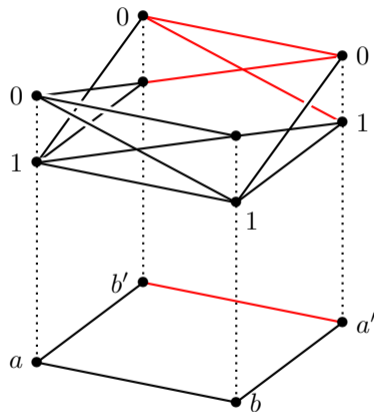


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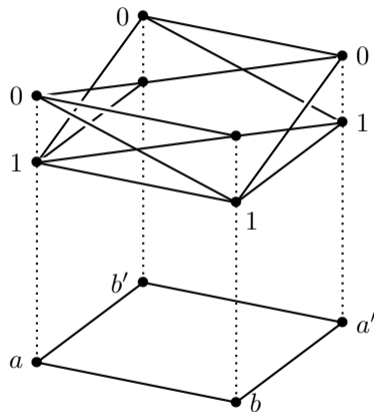


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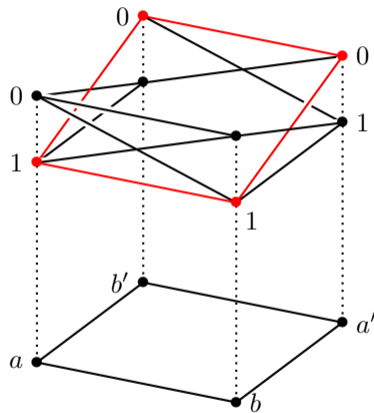


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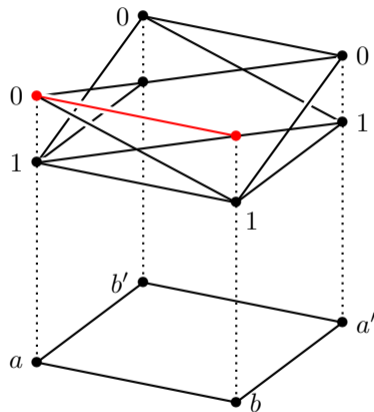


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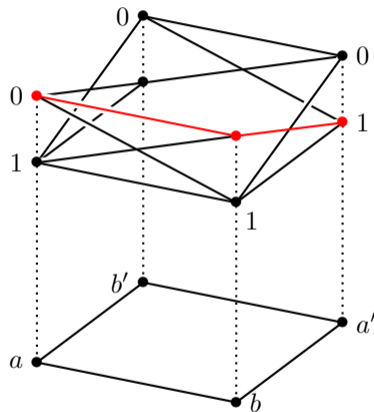


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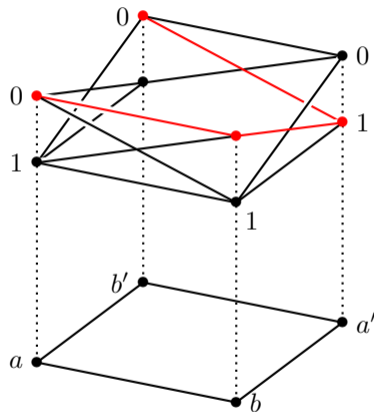


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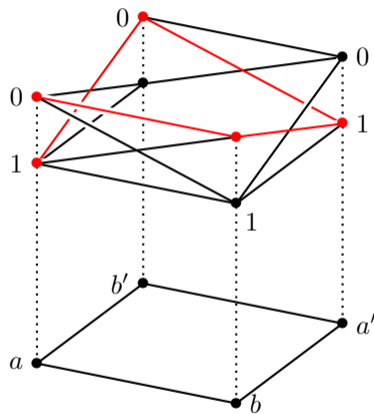


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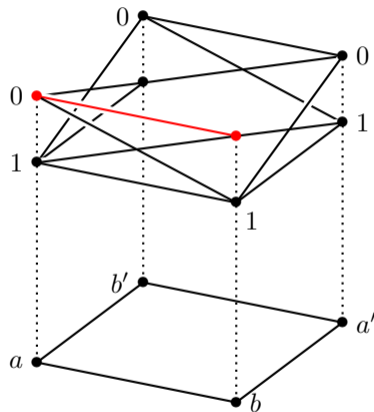


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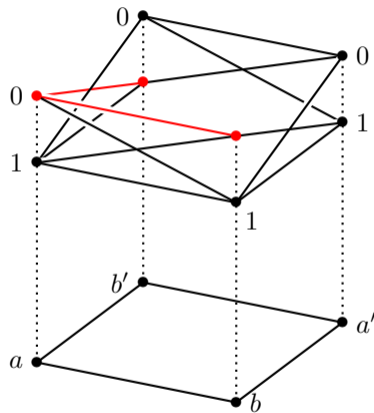


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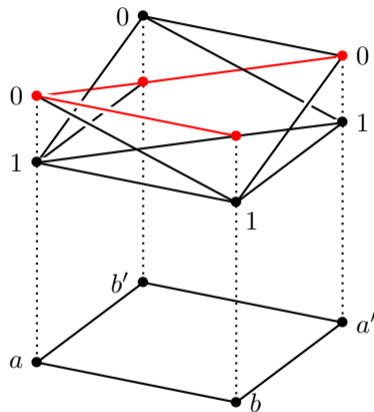


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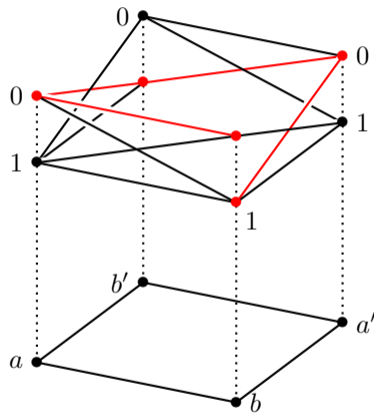


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# Strong Contextuality

| A     | B     | (0,0) | (1,0) | (0,1) | (1,1) |
|-------|-------|-------|-------|-------|-------|
| $a_1$ | $b_1$ | 1     | 0     | 0     | 1     |
| $a_1$ | $b_2$ | 1     | 0     | 0     | 1     |
| $a_2$ | $b_1$ | 1     | 0     | 0     | 1     |
| $a_2$ | $b_2$ | 0     | 1     | 1     | 0     |

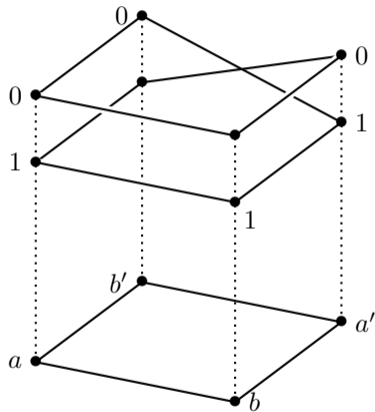
The PR Box

# Bundle Pictures

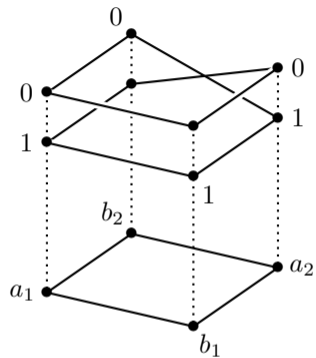
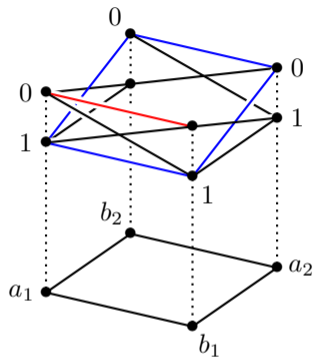
## Strong Contextuality

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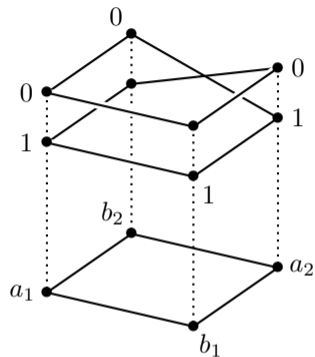
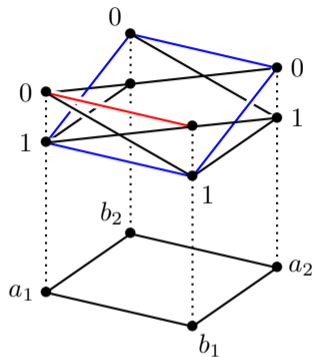


# Visualizing Contextuality



The Hardy table and the PR box as bundles

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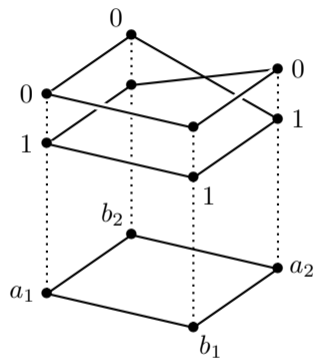
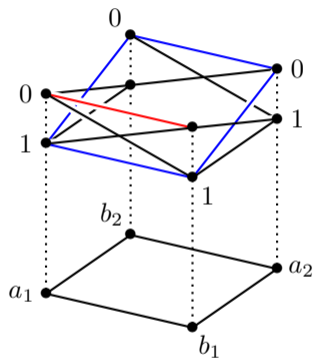


The Hardy table and the PR box as bundles

A hierarchy of degrees of contextuality:

$$\text{Bell} < \text{Hardy} < \text{GHZ}$$

# Visualizing Contextuality



The Hardy table and the PR box as bundles

# Degrees of contextuality



## Degrees of contextuality

Firstly, we say that a global assignment  $t \in O^X$  is **consistent with the support** of a model if for all  $C' \in \mathcal{M}$ ,  $t|_{C'}$  is in the support at  $C'$ .

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- It is **strongly contextual** if its support has **no global section**; that is, there is no consistent global assignment.

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Obviously, strong non-locality implies logical non-locality.

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Thus in terms of well-known examples, we have

$$\text{Bell} < \text{Hardy} < \text{GHZ}$$